

## ECE 382 Embedded Systems I

Conditional jumps support program branching relative to the PC and do not affect the status bits. The possible jump range is from -511 to +512 words relative to the PC value at the jump instruction. The 10-bit program-counter offset is treated as a signed 10-bit value that is doubled and added to the program counter:

$$PC_{\text{new}} = PC_{\text{old}} + 2 + PC_{\text{offset}} \times 2$$

Word Operations (W) = 0

Byte Operations (B) = 1

**Table 1. Source Addressing Modes (As)**

Address Mode	*As	Registers	Syntax	Operation
Register	00	R0-R2, R4-R15	$Rn$	Register Contents.
0	00	R3	#0	0 Constant
Symbolic	01	R0	$addr$	(PC+next word) points to operand. ( $x(PC)$ )
Indexed	01	R1, R4-R15	$x(Rn)$	( $Rn+x$ ) points to operand. $x$ is next code word.
Absolute	01	R2	$\&addr$	Next code word is the absolute address. ( $x(SR)$ )
+1	01	R3	#1	+1 Constant
Indirect	10	R0-R1, R4-R15	$@Rn$	$Rn$ points to operand.
+4	10	R2	#4	+4 Constant
+2	10	R3	#2	+2 Constant
Immediate	11	R0	# $N$	Next word is the constant $N$ . (@PC+)
Indirect auto-inc	11	R1, R4-R15	$@Rn+$	$Rn$ points to operand, $Rn$ is incremented (1 or 2).
+8	11	R2	#8	+8 Constant
-1	11	R3	#-1	-1 Constant

\*Bits 4 and 5 in Single (Table 3) and Double (Table 5) Operand Instructions

**Table 2. Destination Addressing Modes (Ad)**

Address Mode	*Ad	Registers	Syntax	Operation
Register	0	R0-R2, R4-R15	$Rn$	Register Contents.
0	0	R3	#0	Bit bucket
Symbolic	1	R0	$addr$	(PC+next word) points to operand. ( $x(PC)$ )
Indexed	1	R1, R4-R15	$x(Rn)$	( $Rn+x$ ) points to operand. $x$ is next code word.
Absolute	1	R2	$\&addr$	Next code word is the absolute address. ( $x(SR)$ )

\*Bit 7 in (Table 5) Operand Instructions

**Table 3. Single Operand Instructions**

9-bit Opcode										b/w	As	D/S Register				
Mnemonic	Opcode									V	N	Z	C	Operation	Description	
RRC	0	0	0	1	0	0	0	0	0	•	•	•	•	C→MSB→...LSB→C	Roll dst right through C	
SWPB	0	0	0	1	0	0	0	0	1	-	-	-	-	Swap bytes	Swap bytes	
RRA	0	0	0	1	0	0	0	1	0	0	•	•	•	MSB→MSB→...LSB→C	Roll destination right	
SXT	0	0	0	1	0	0	0	1	1	0	•	•	z	bit 7→bit 8...bit 15	Sign extend destination	
PUSH	0	0	0	1	0	0	1	0	0	-	-	-	-	SP-2→SP, src→@SP	Push source on stack	
CALL	0	0	0	1	0	0	1	0	1	-	-	-	-	SP-2→SP, PC+2→@SP, dst→PC	Subroutine call	
RETI	0	0	0	1	0	0	1	1	0	•	•	•	•	@SP+→SR, @SP+→PC	Return from interrupt	

**Table 4. Jump Instructions**

6-bit Opcode						10-bit, 2's complement PC Offset													
Mnemonic	Opcode					V	N	Z	C	Description									
JNZ/JNE	0	0	1	0	0	-	-	0	-	Jump if not equal									
JZ/JEQ	0	0	1	0	0	-	-	1	-	Jump if equal									
JNC/JLO	0	0	1	0	1	-	-	-	0	Jump if carry flag equal to zero									
JC/JHS	0	0	1	0	1	-	-	-	1	Jump if carry flag equal to one									
JN	0	0	1	1	0	-	1	-	-	Jump if negative (N = 1)									
JGE	0	0	1	1	0	•	•	-	-	Jump if greater than or equal (N = V)									
JL	0	0	1	1	1	•	•	-	-	Jump if lower (N ≠ V)									
JMP	0	0	1	1	1	-	-	-	-	Unconditional jump									

**Table 5. Double Operand Instructions**

4-bit Opcode				Source Register				Ad	b/w	As	Destination Register					
Mnemonic	Opcode			V	N	Z	C	Operation				Description				
MOV	0	1	0	0	-	-	-	-	src→dst				Move source to destination			
ADD	0	1	0	1	•	•	•	•	src+dst→dst				Add source to destination			
ADDC	0	1	1	0	•	•	•	•	src+dst+C→dst				Add src and C to dst			
SUBC	0	1	1	1	•	•	•	•	dst+.not.src+C→dst				Subtract src and NOT C from dst			
SUB	1	0	0	0	•	•	•	•	dst+.not.src+1→dst				Subtract source from destination			
CMP	1	0	0	1	•	•	•	•	dst-src				Compare source to destination			
DADD	1	0	1	0	•	•	•	•	src+dst+C→dst(dec)				Decimal add src and C to dst			
BIT	1	0	1	1	0	•	•	z	src.and.dst				Test bits in destination			
BIC	1	1	0	0	-	-	-	-	.not.src.and.dst→dst				Clear bits in destination			
BIS	1	1	0	1	-	-	-	-	src.or.dst→dst				Set bits in destination			
XOR	1	1	1	0	•	•	•	z	src.xor.dst→dst				XOR source with destination			
AND	1	1	1	1	0	•	•	z	src.and.dst→dst				AND source with destination			

Status Register: • = bit affected, - = bit not affected, 0 = cleared, 1 = set, z = same as Z

**Table 6. Source Operands Using Status (R2) and Constant Generator (R3) Registers**

Register	As	Addr Mode	Syntax	Constant	Remarks
R2	00	Register	-	-	Register mode
R2	01	x(R2)	addr	(0)	Absolute address mode, next word contains address
R2	10	@R2	#4	0x0004	+4
R2	11	@R2+	#8	0x0008	+8
R3	00	R3	#0	0x0000	0
R3	01	x(R3)	#1	0x0001	+1, No extension word
R3	10	@R3	#2	0x0002	+2
R3	11	@R3+	#-1	0xFFFF	-1



### 3.4.4.3 Format-III (Jump) Instruction Cycles and Lengths

All jump instructions require one code word, and take two CPU cycles to execute, regardless of whether the jump is taken or not.

**Table 3-15. Format-II Instruction Cycles and Lengths**

Single Operand

Addressing Mode	No. of Cycles			Length of Instruction	Example
	RRA, RRC SWPB, SXT	PUSH	CALL		
Rn	1	3	4	1	SWPB R5
@Rn	3	4	4	1	RRC @R9
@Rn+	3	5	5	1	SWPB @R10+
#N	(See note)	4	5	2	CALL #0F000h
X(Rn)	4	5	5	2	CALL 2 (R7)
EDE	4	5	5	2	PUSH EDE
&EDE	4	5	5	2	SXT &EDE

**Table 3-16. Format 1 Instruction Cycles and Lengths**

Double Operand

Addressing Mode		No. of Cycles	Length of Instruction		Example
Src	Dst				
Rn	Rm	1	1	MOV	R5, R8
	PC	2	1	BR	R9
	x(Rm)	4	2	ADD	R5, 4 (R6)
	EDE	4	2	XOR	R8, EDE
	&EDE	4	2	MOV	R5, &EDE
@Rn	Rm	2	1	AND	@R4, R5
	PC	2	1	BR	@R8
	x(Rm)	5	2	XOR	@R5, 8 (R6)
	EDE	5	2	MOV	@R5, EDE
	&EDE	5	2	XOR	@R5, &EDE
@Rn+	Rm	2	1	ADD	@R5+, R6
	PC	3	1	BR	@R9+
	x(Rm)	5	2	XOR	@R5, 8 (R6)
	EDE	5	2	MOV	@R9+, EDE
	&EDE	5	2	MOV	@R9+, &EDE
#N	Rm	2	2	MOV	#20, R9
	PC	3	2	BR	#2AEh
	x(Rm)	5	3	MOV	#0300h, 0 (SP)
	EDE	5	3	ADD	#33, EDE
	&EDE	5	3	ADD	#33, &EDE
x(Rn)	Rm	3	2	MOV	2 (R5), R7
	PC	3	2	BR	2 (R6)
	TONI	6	3	MOV	4 (R7), TONI
	x(Rm)	6	3	ADD	4 (R4), 6 (R9)
	&TONI	6	3	MOV	2 (R4), &TONI
EDE	Rm	3	2	AND	EDE, R6
	PC	3	2	BR	EDE
	TONI	6	3	CMP	EDE, TONI
	x(Rm)	6	3	MOV	EDE, 0 (SP)
	&TONI	6	3	MOV	EDE, &TONI
&EDE	Rm	3	2	MOV	&EDE, R8
	PC	3	2	BRA	&EDE
	TONI	6	3	MOV	&EDE, TONI
	x(Rm)	6	3	MOV	&EDE, 0 (SP)
	&TONI	6	3	MOV	&EDE, &TONI

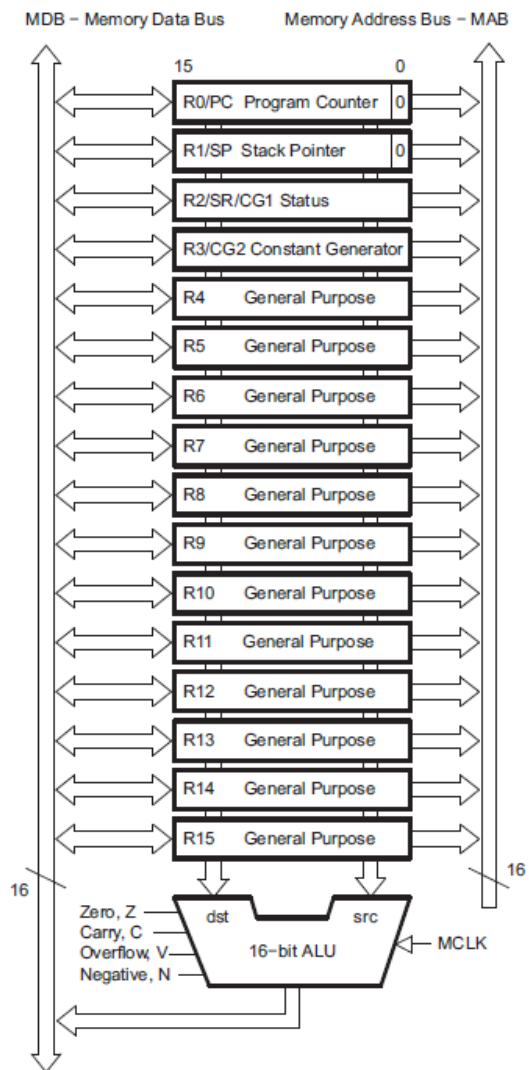


Figure 3-1. CPU Block Diagram

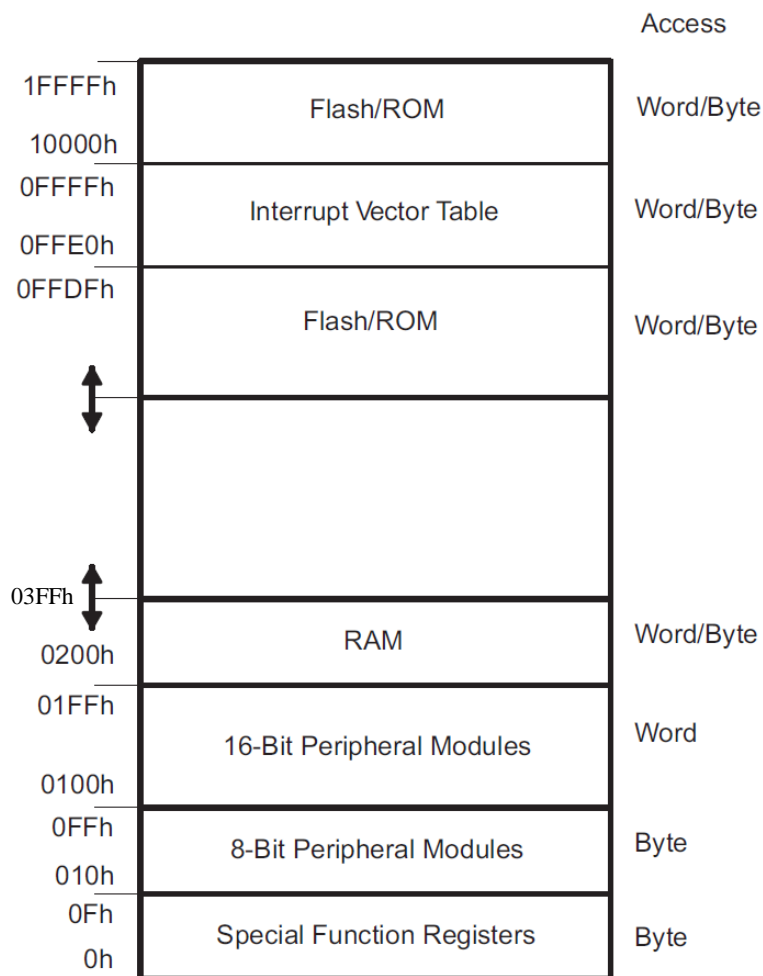
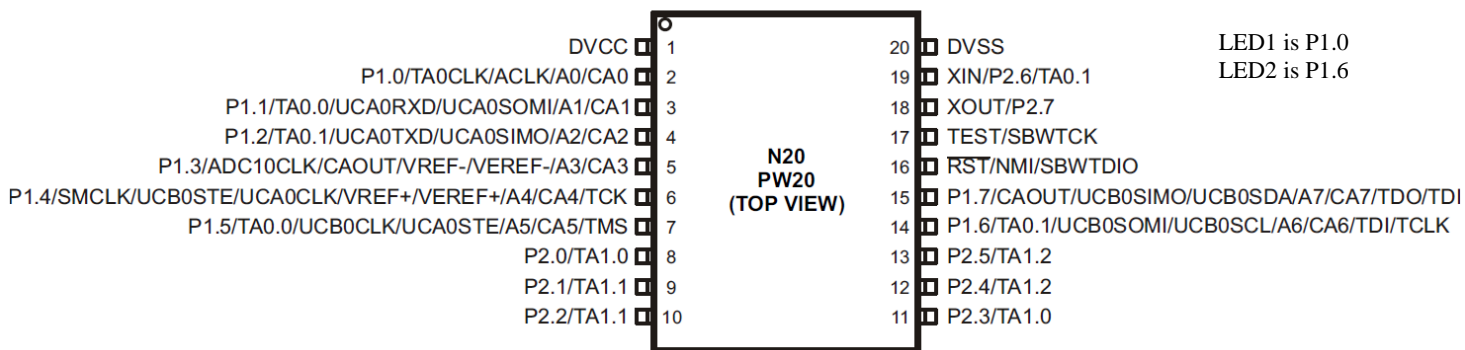


Figure 3-6. Status Register Bits

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
Reserved							V	SCG1	SCG0	OSC OFF	CPU OFF	GIE	N	Z	C	
rw-0							rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0



### 8.2.1 Input Register PxIN

Each bit in each PxIN register reflects the value of the input signal at the corresponding I/O pin when the pin is configured as I/O function.

- Bit = 0: The input is low
- Bit = 1: The input is high

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**NOTE: Writing to Read-Only Registers PxIN**

Writing to these read-only registers results in increased current consumption while the write attempt is active.

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### 8.2.2 Output Registers PxOUT

Each bit in each PxOUT register is the value to be output on the corresponding I/O pin when the pin is configured as I/O function, output direction, and the pullup/down resistor is disabled.

- Bit = 0: The output is low
- Bit = 1: The output is high

If the pin's pullup/pulldown resistor is enabled, the corresponding bit in the PxOUT register selects pullup or pulldown.

- Bit = 0: The pin is pulled down
- Bit = 1: The pin is pulled up

### 8.2.4 Pullup/Pulldown Resistor Enable Registers PxREN

Each bit in each PxREN register enables or disables the pullup/pulldown resistor of the corresponding I/O pin. The corresponding bit in the PxOUT register selects if the pin is pulled up or pulled down.

- Bit = 0: Pullup/pulldown resistor disabled
- Bit = 1: Pullup/pulldown resistor enabled

**Table 16. Port P1 (P1.0 to P1.2) Pin Functions**

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS AND SIGNALS <sup>(1)</sup>				
			P1DIR.x	P1SEL.x	P1SEL2.x	ADC10AE.x INCH.x=1 <sup>(2)</sup>	CAPD.y
P1.0/	0	P1.x (I/O)	I: 0; O: 1	0	0	0	0
TA0CLK/		TA0.TACLK	0	1	0	0	0
ACLK/		ACLK	1	1	0	0	0
A0 <sup>(2)</sup> /		A0	X	X	X	1 (y = 0)	0
CA0/		CA0	X	X	X	0	1 (y = 0)
Pin Osc		Capacitive sensing	X	0	1	0	0
P1.1/	1	P1.x (I/O)	I: 0; O: 1	0	0	0	0
TA0.0/		TA0.0	1	1	0	0	0
		TA0.CCI0A	0	1	0	0	0
UCA0RXD/		UCA0RXD	from USCI	1	1	0	0
UCA0SOMI/		UCA0SOMI	from USCI	1	1	0	0
A1 <sup>(2)</sup> /		A1	X	X	X	1 (y = 1)	0
CA1/		CA1	X	X	X	0	1 (y = 1)
Pin Osc	Capacitive sensing	X	0	1	0	0	
P1.2/	2	P1.x (I/O)	I: 0; O: 1	0	0	0	0
TA0.1/		TA0.1	1	1	0	0	0
		TA0.CCI1A	0	1	0	0	0
UCA0TXD/		UCA0TXD	from USCI	1	1	0	0
UCA0SIMO/		UCA0SIMO	from USCI	1	1	0	0
A2 <sup>(2)</sup> /		A2	X	X	X	1 (y = 2)	0
CA2/		CA2	X	X	X	0	1 (y = 2)
Pin Osc		Capacitive sensing	X	0	1	0	0

(1) X = don't care

(2) MSP430G2x53 devices only

**Table 17. Port P1 (P1.3) Pin Functions**

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS AND SIGNALS <sup>(1)</sup>					
			P1DIR.x	P1SEL.x	P1SEL2.x	ADC10AE.x INCH.x=1 <sup>(2)</sup>	CAPD.y	
P1.3/ ADC10CLK <sup>(2)</sup> / CAOUT/ A3 <sup>(2)</sup> / VREF- <sup>(2)</sup> / VEREF- <sup>(2)</sup> / CA3/ Pin Osc	3	P1.x (I/O)	I: 0; O: 1	0	0	0	0	0
ADC10CLK		1	1	0	0	0		
CAOUT		1	1	1	0	0		
A3		X	X	X	1 (y = 3)	0		
VREF-		X	X	X	1	0		
VEREF-		X	X	X	1	0		
CA3		X	X	X	0	1 (y = 3)		
Capacitive sensing		X	0	1	0	0		

(1) X = don't care

(2) MSP430G2x53 devices only

**Table 18. Port P1 (P1.4) Pin Functions**

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS AND SIGNALS <sup>(1)</sup>					
			P1DIR.x	P1SEL.x	P1SEL2.x	ADC10AE.x INCH.x=1 <sup>(2)</sup>	JTAG Mode	CAPD.y
P1.4/ SMCLK/ UCB0STE/ UCA0CLK/ VREF+ <sup>(2)</sup> / VEREF+ <sup>(2)</sup> / A4 <sup>(2)</sup> / CA4/ TCK/ Pin Osc	4	P1.x (I/O)	I: 0; O: 1	0	0	0	0	0
SMCLK		1	1	0	0	0		
UCB0STE		from USCI	1	1	0	0		
UCA0CLK		from USCI	1	1	0	0		
VREF+		X	X	X	1	0		
VEREF+		X	X	X	1	0		
A4		X	X	X	1 (y = 4)	0		
CA4		X	X	X	0	0	1 (y = 4)	
TCK		X	X	X	0	1	0	
Capacitive sensing		X	0	1	0	0	0	

(1) X = don't care

(2) MSP430G2x53 devices only

**Table 19. Port P1 (P1.5 to P1.7) Pin Functions**

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS AND SIGNALS <sup>(1)</sup>					
			P1DIR.x	P1SEL.x	P1SEL2.x	ADC10AE.x INCH.x=1 <sup>(2)</sup>	JTAG Mode	CAPD.y
P1.5/ TA0.0/	5	P1.x (I/O)	I: 0; O: 1	0	0	0	0	0
UCB0CLK/		TA0.0	1	1	0	0	0	0
UCA0STE/		UCB0CLK	from USCI	1	1	0	0	0
A5 <sup>(2)</sup> /		UCA0STE	from USCI	1	1	0	0	0
CA5		A5	X	X	X	1 (y = 5)	0	0
TMS		CA5	X	X	X	0	0	1 (y = 5)
Pin Osc		TMS	X	X	X	0	1	0
		Capacitive sensing	X	0	1	0	0	0
P1.6/ TA0.1/	6	P1.x (I/O)	I: 0; O: 1	0	0	0	0	0
UCB0SOMI/		TA0.1	1	1	0	0	0	0
UCB0SCL/		UCB0SOMI	from USCI	1	1	0	0	0
A6 <sup>(2)</sup> /		UCB0SCL	from USCI	1	1	0	0	0
CA6		A6	X	X	X	1 (y = 6)	0	0
TDI/TCLK/		CA6	X	X	X	0	0	1 (y = 6)
Pin Osc		TDI/TCLK	X	X	X	0	1	0
		Capacitive sensing	X	0	1	0	0	0
P1.7/ UCB0SIMO/	7	P1.x (I/O)	I: 0; O: 1	0	0	0	0	0
UCB0SDA/		UCB0SIMO	from USCI	1	1	0	0	0
A7 <sup>(2)</sup> /		UCB0SDA	from USCI	1	1	0	0	0
CA7		A7	X	X	X	1 (y = 7)	0	0
CAOUT		CA7	X	X	X	0	0	1 (y = 7)
TDO/TDI/		CAOUT	1	1	0	0	0	0
Pin Osc		TDO/TDI	X	X	X	0	1	0
		Capacitive sensing	X	0	1	0	0	0

(1) X = don't care

(2) MSP430G2x53 devices only



**Table 5. Interrupt Sources, Flags, and Vectors**

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Power-Up External Reset Watchdog Timer+ Flash key violation PC out-of-range <sup>(1)</sup>	PORIFG RSTIFG WDTIFG KEYV <sup>(2)</sup>	Reset	0FFFEh	31, highest
NMI Oscillator fault Flash memory access violation	NMIIFG OFIFG ACCVIFG <sup>(2)(3)</sup>	(non)-maskable (non)-maskable (non)-maskable	0FFFCh	30
Timer1_A3	TA1CCR0 CCIFG <sup>(4)</sup>	maskable	0FFFAh	29
Timer1_A3	TA1CCR2 TA1CCR1 CCIFG, TAIFG <sup>(2)(4)</sup>	maskable	0FFF8h	28
Comparator_A+	CAIFG <sup>(4)</sup>	maskable	0FFF6h	27
Watchdog Timer+	WDTIFG	maskable	0FFF4h	26
Timer0_A3	TA0CCR0 CCIFG <sup>(4)</sup>	maskable	0FFF2h	25
Timer0_A3	TA0CCR2 TA0CCR1 CCIFG, TAIFG <sup>(5)(4)</sup>	maskable	0FFF0h	24
USCI_A0/USCI_B0 receive USCI_B0 I2C status	UCA0RXIFG, UCB0RXIFG <sup>(2)(5)</sup>	maskable	0FFEEh	23
USCI_A0/USCI_B0 transmit USCI_B0 I2C receive/transmit	UCA0TXIFG, UCB0TXIFG <sup>(2)(6)</sup>	maskable	0FFECh	22
ADC10 (MSP430G2x53 only)	ADC10IFG <sup>(4)</sup>	maskable	0FFEAh	21
			0FFE8h	20
I/O Port P2 (up to eight flags)	P2IFG.0 to P2IFG.7 <sup>(2)(4)</sup>	maskable	0FFE6h	19
I/O Port P1 (up to eight flags)	P1IFG.0 to P1IFG.7 <sup>(2)(4)</sup>	maskable	0FFE4h	18
			0FFE2h	17
			0FFE0h	16
See <sup>(7)</sup>			0FFDEh	15
See <sup>(8)</sup>			0FFDEh to 0FFC0h	14 to 0, lowest

**NOTE: Initializing or Re-Configuring the USCI Module**

The recommended USCI initialization/re-configuration process is:

1. Set UCSWRST (BIS.B #UCSWRST,&UCxCTL1)
2. Initialize all USCI registers with UCSWRST=1 (including UCxCTL1)
3. Configure ports
4. Clear UCSWRST via software (BIC.B #UCSWRST,&UCxCTL1)
5. Enable interrupts (optional) via UCxRXIE and/or UCxTXIE

### 16.4.1 UCAXCTL0, USCI\_Ax Control Register 0, UCbxCTL0, USCI\_Bx Control Register 0

	7	6	5	4	3	2	1	0
	UCCKPH	UCCKPL	UCMSB	UC7BIT	UCMST	UCMODEx		UCSYNC=1
	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	
UCCKPH	Bit 7	Clock phase select. 0 Data is changed on the first UCLK edge and captured on the following edge. 1 Data is captured on the first UCLK edge and changed on the following edge.						
UCCKPL	Bit 6	Clock polarity select. 0 The inactive state is low. 1 The inactive state is high.						
UCMSB	Bit 5	MSB first select. Controls the direction of the receive and transmit shift register. 0 LSB first 1 MSB first						
UC7BIT	Bit 4	Character length. Selects 7-bit or 8-bit character length. 0 8-bit data 1 7-bit data						
UCMST	Bit 3	Master mode select 0 Slave mode 1 Master mode						
UCMODEx	Bits 2-1	USCI mode. The UCMODEx bits select the synchronous mode when UCSYNC = 1. 00 3-pin SPI 01 4-pin SPI with UCxSTE active high: slave enabled when UCxSTE = 1 10 4-pin SPI with UCxSTE active low: slave enabled when UCxSTE = 0 11 I <sup>2</sup> C mode						
UCSYNC	Bit 0	Synchronous mode enable 0 Asynchronous mode 1 Synchronous mode						

### 15.4.2 UCAXCTL1, USCI\_Ax Control Register 1

	7	6	5	4	3	2	1	0
	UCSSELx		UCRXEIE	UCBRKIE	UCDORM	UCTXADDR	UCTXBRK	UCSWRST
	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-1
UCSSELx	Bits 7-6	USCI clock source select. These bits select the BRCLK source clock. 00 UCLK 01 ACLK 10 SMCLK 11 SMCLK						
UCRXEIE	Bit 5	Receive erroneous-character interrupt-enable 0 Erroneous characters rejected and UCAXRXIFG is not set 1 Erroneous characters received will set UCAXRXIFG						
UCBRKIE	Bit 4	Receive break character interrupt-enable 0 Received break characters do not set UCAXRXIFG. 1 Received break characters set UCAXRXIFG.						
UCDORM	Bit 3	Dormant. Puts USCI into sleep mode. 0 Not dormant. All received characters will set UCAXRXIFG. 1 Dormant. Only characters that are preceded by an idle-line or with address bit set will set UCAXRXIFG. In UART mode with automatic baud rate detection only the combination of a break and synch field will set UCAXRXIFG.						
UCTXADDR	Bit 2	Transmit address. Next frame to be transmitted will be marked as address depending on the selected multiprocessor mode. 0 Next frame transmitted is data 1 Next frame transmitted is an address						
UCTXBRK	Bit 1	Transmit break. Transmits a break with the next write to the transmit buffer. In UART mode with automatic baud rate detection 055h must be written into UCAXTXBUF to generate the required break/synch fields. Otherwise 0h must be written into the transmit buffer. 0 Next frame transmitted is not a break 1 Next frame transmitted is a break or a break/synch						
UCSWRST	Bit 0	Software reset enable 0 Disabled. USCI reset released for operation. 1 Enabled. USCI logic held in reset state.						

### 15.4.3 UCAXBR0, USCI\_Ax Baud Rate Control Register 0

7	6	5	4	3	2	1	0
UCBRx							
rw	rw	rw	rw	rw	rw	rw	rw

### 15.4.4 UCAXBR1, USCI\_Ax Baud Rate Control Register 1

7	6	5	4	3	2	1	0
UCBRx							
rw	rw	rw	rw	rw	rw	rw	rw

UCBRx 7-0 Clock prescaler setting of the Baud rate generator. The 16-bit value of (UCAXBR0 + UCAXBR1 × 256) forms the prescaler value.

### 15.4.5 UCAXMCTL, USCI\_Ax Modulation Control Register

7	6	5	4	3	2	1	0
UCBRFx				UCBRsX			UCOS16
rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0	rw-0

UCBRFx Bits 7-4 First modulation stage select. These bits determine the modulation pattern for BITCLK16 when UCOS16 = 1. Ignored with UCOS16 = 0. [Table 15-3](#) shows the modulation pattern.

UCBRsX Bits 3-1 Second modulation stage select. These bits determine the modulation pattern for BITCLK. [Table 15-2](#) shows the modulation pattern.

UCOS16 Bit 0 Oversampling mode enabled  
 0 Disabled  
 1 Enabled

### 15.4.7 UCAXRXBUF, USCI\_Ax Receive Buffer Register

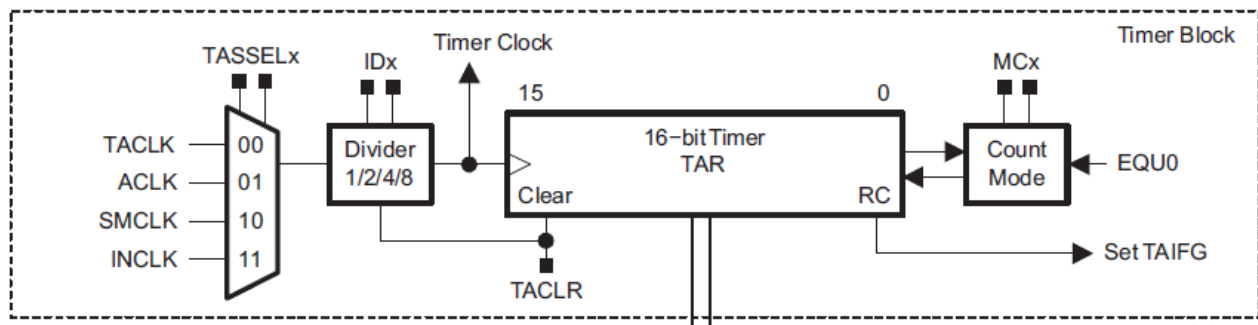
7	6	5	4	3	2	1	0
UCRXBUFx							
rw	rw	rw	rw	rw	rw	rw	rw

UCRXBUFx Bits 7-0 The receive-data buffer is user accessible and contains the last received character from the receive shift register. Reading UCAXRXBUF resets the receive-error bits, the UCADDR or UCIDLE bit, and UCAXRXIFG. In 7-bit data mode, UCAXRXBUF is LSB justified and the MSB is always reset.

### 15.4.8 UCAXTXBUF, USCI\_Ax Transmit Buffer Register

7	6	5	4	3	2	1	0
UCTXBUFx							
rw	rw	rw	rw	rw	rw	rw	rw

UCTXBUFx Bits 7-0 The transmit data buffer is user accessible and holds the data waiting to be moved into the transmit shift register and transmitted on UCAXTXD. Writing to the transmit data buffer clears UCAXTXIFG. The MSB of UCAXTXBUF is not used for 7-bit data and is reset.



### 12.3.1 TACTL, Timer\_A Control Register

15	14	13	12	11	10	9	8
Unused						TASSSELx	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
IDx		MCx		Unused	TACLRL	TAIE	TAIFG
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

<b>Unused</b>	Bits 15-10	Unused
<b>TASSSELx</b>	Bits 9-8	Timer_A clock source select
	00	TACLK
	01	ACLK
	10	SMCLK
	11	INCLK (INCLK is device-specific and is often assigned to the inverted TBCLK) (see the device-specific data sheet)
<b>IDx</b>	Bits 7-6	Input divider. These bits select the divider for the input clock.
	00	/1
	01	/2
	10	/4
	11	/8
<b>MCx</b>	Bits 5-4	Mode control. Setting MCx = 00h when Timer_A is not in use conserves power.
	00	Stop mode: the timer is halted.
	01	Up mode: the timer counts up to TACCR0.
	10	Continuous mode: the timer counts up to 0FFFFh.
	11	Up/down mode: the timer counts up to TACCR0 then down to 0000h.
<b>Unused</b>	Bit 3	Unused
<b>TACLRL</b>	Bit 2	Timer_A clear. Setting this bit resets TAR, the clock divider, and the count direction. The TACLRL bit is automatically reset and is always read as zero.
<b>TAIE</b>	Bit 1	Timer_A interrupt enable. This bit enables the TAIFG interrupt request.
	0	Interrupt disabled
	1	Interrupt enabled
<b>TAIFG</b>	Bit 0	Timer_A interrupt flag
	0	No interrupt pending
	1	Interrupt pending

### 12.3.4 TACCTLx, Capture/Compare Control Register

15	14	13	12	11	10	9	8
<b>CMx</b>		<b>CCISx</b>		<b>SCS</b>	<b>SCCI</b>	<b>Unused</b>	<b>CAP</b>
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	r	r0	rw-(0)
7	6	5	4	3	2	1	0
<b>OUTMODx</b>			<b>CCIE</b>	<b>CCI</b>	<b>OUT</b>	<b>COV</b>	<b>CCIFG</b>
rw-(0)	rw-(0)	rw-(0)	rw-(0)	r	rw-(0)	rw-(0)	rw-(0)

<b>CMx</b>	Bit 15-14	Capture mode 00 No capture 01 Capture on rising edge 10 Capture on falling edge 11 Capture on both rising and falling edges
<b>CCISx</b>	Bit 13-12	Capture/compare input select. These bits select the TACCRx input signal. See the device-specific data sheet for specific signal connections. 00 CC1xA 01 CC1xB 10 GND 11 V <sub>CC</sub>
<b>SCS</b>	Bit 11	Synchronize capture source. This bit is used to synchronize the capture input signal with the timer clock. 0 Asynchronous capture 1 Synchronous capture
<b>SCCI</b>	Bit 10	Synchronized capture/compare input. The selected CCI input signal is latched with the EQUx signal and can be read via this bit
<b>Unused</b>	Bit 9	Unused. Read only. Always read as 0.
<b>CAP</b>	Bit 8	Capture mode 0 Compare mode 1 Capture mode
<b>OUTMODx</b>	Bits 7-5	Output mode. Modes 2, 3, 6, and 7 are not useful for TACCR0, because EQUx = EQU0. 000 OUT bit value 001 Set 010 Toggle/reset 011 Set/reset 100 Toggle 101 Reset 110 Toggle/set 111 Reset/set
<b>CCIE</b>	Bit 4	Capture/compare interrupt enable. This bit enables the interrupt request of the corresponding CCIFG flag. 0 Interrupt disabled 1 Interrupt enabled
<b>CCI</b>	Bit 3	Capture/compare input. The selected input signal can be read by this bit.
<b>OUT</b>	Bit 2	Output. For output mode 0, this bit directly controls the state of the output. 0 Output low 1 Output high
<b>COV</b>	Bit 1	Capture overflow. This bit indicates a capture overflow occurred. COV must be reset with software. 0 No capture overflow occurred 1 Capture overflow occurred
<b>CCIFG</b>	Bit 0	Capture/compare interrupt flag 0 No interrupt pending 1 Interrupt pending

### 12.3.5 TAIV, Timer\_A Interrupt Vector Register

15	14	13	12	11	10	9	8
0	0	0	0	0	0	0	0
r0	r0	r0	r0	r0	r0	r0	r0
7	6	5	4	3	2	1	0
0	0	0	0	TAIVx			0
r0	r0	r0	r0	r-(0)	r-(0)	r-(0)	r0

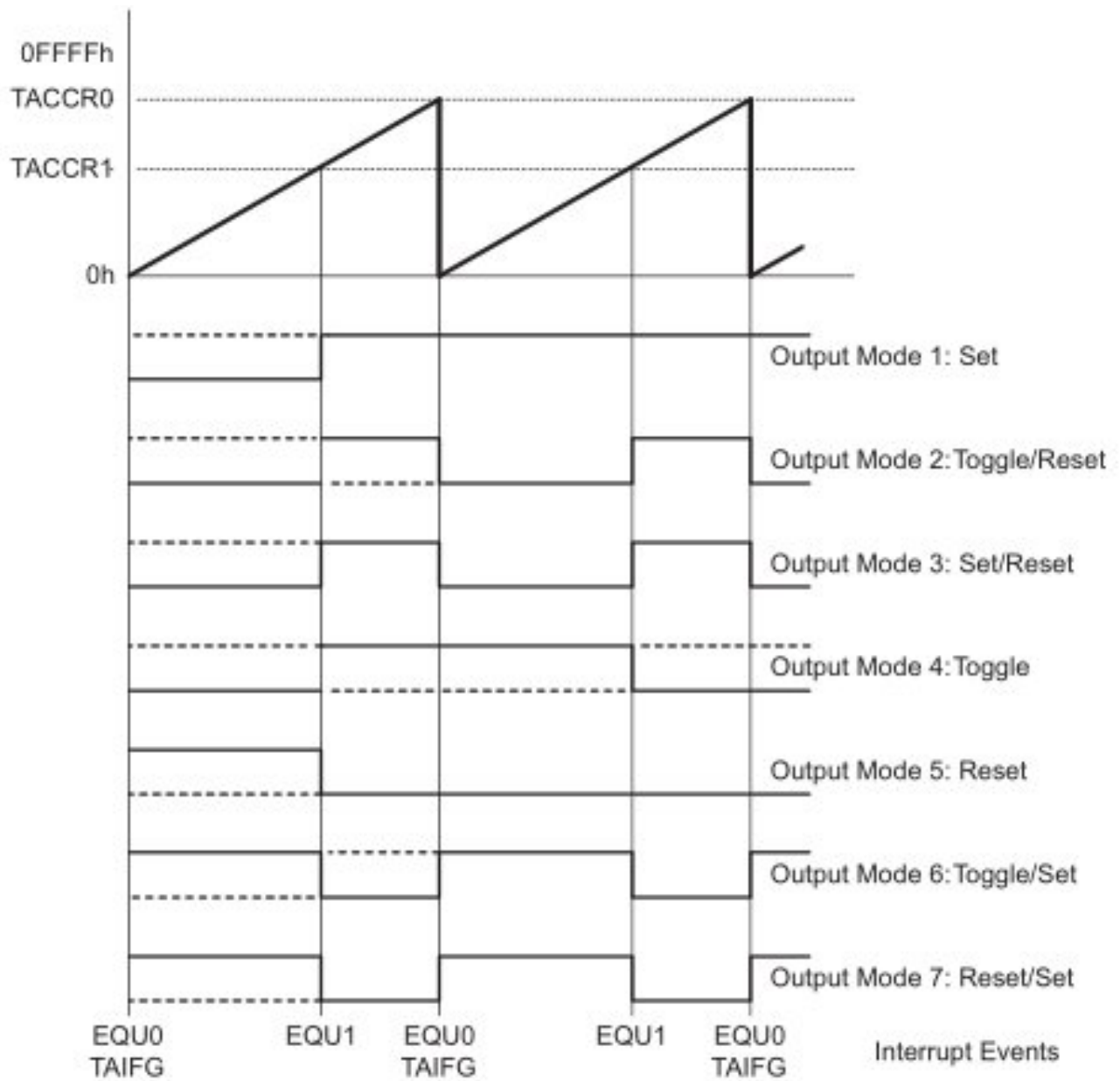
TAIVx Bits 15-0 Timer\_A interrupt vector value

TAIV Contents	Interrupt Source	Interrupt Flag	Interrupt Priority
00h	No interrupt pending	-	
02h	Capture/compare 1	TACCR1 CCIFG	Highest
04h	Capture/compare 2 <sup>(1)</sup>	TACCR2 CCIFG	
06h	Reserved	-	
08h	Reserved	-	
0Ah	Timer overflow	TAIFG	
0Ch	Reserved	-	
0Eh	Reserved	-	Lowest

<sup>(1)</sup> Not implemented in MSP430x20xx devices

**Table 12-2. Output Modes**

OUTMODx	Mode	Description
000	Output	The output signal OUTx is defined by the OUTx bit. The OUTx signal updates immediately when OUTx is updated.
001	Set	The output is set when the timer <i>counts</i> to the TACCRx value. It remains set until a reset of the timer, or until another output mode is selected and affects the output.
010	Toggle/Reset	The output is toggled when the timer <i>counts</i> to the TACCRx value. It is reset when the timer <i>counts</i> to the TACCR0 value.
011	Set/Reset	The output is set when the timer <i>counts</i> to the TACCRx value. It is reset when the timer <i>counts</i> to the TACCR0 value.
100	Toggle	The output is toggled when the timer <i>counts</i> to the TACCRx value. The output period is double the timer period.
101	Reset	The output is reset when the timer <i>counts</i> to the TACCRx value. It remains reset until another output mode is selected and affects the output.
110	Toggle/Set	The output is toggled when the timer <i>counts</i> to the TACCRx value. It is set when the timer <i>counts</i> to the TACCR0 value.
111	Reset/Set	The output is reset when the timer <i>counts</i> to the TACCRx value. It is set when the timer <i>counts</i> to the TACCR0 value.



**Figure 12-12. Output Example—Timer in Up Mode**

### 22.3.1 ADC10CTL0, ADC10 Control Register 0

15	14	13	12	11	10	9	8
SREFx		ADC10SHTx			ADC10SR	REFOUT	REFBURST
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
MSC	REF2_5V	REFON	ADC10ON	ADC10IE	ADC10IFG	ENC	ADC10SC
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

Can be modified only when ENC = 0

<b>SREFx</b>	Bits 15-13	Select reference. 000 $V_{R+} = V_{CC}$ and $V_{R-} = V_{SS}$ 001 $V_{R+} = V_{REF+}$ and $V_{R-} = V_{SS}$ 010 $V_{R+} = V_{eREF+}$ and $V_{R-} = V_{SS}$ . Devices with $V_{eREF+}$ only. 011 $V_{R+} =$ Buffered $V_{eREF+}$ and $V_{R-} = V_{SS}$ . Devices with $V_{eREF+}$ pin only. 100 $V_{R+} = V_{CC}$ and $V_{R-} = V_{REF-} / V_{eREF-}$ . Devices with $V_{eREF-}$ pin only. 101 $V_{R+} = V_{REF+}$ and $V_{R-} = V_{REF-} / V_{eREF-}$ . Devices with $V_{eREF+/-}$ pins only. 110 $V_{R+} = V_{eREF+}$ and $V_{R-} = V_{REF-} / V_{eREF-}$ . Devices with $V_{eREF+/-}$ pins only. 111 $V_{R+} =$ Buffered $V_{eREF+}$ and $V_{R-} = V_{REF-} / V_{eREF-}$ . Devices with $V_{eREF+/-}$ pins only.
<b>ADC10SHTx</b>	Bits 12-11	ADC10 sample-and-hold time 00 $4 \times$ ADC10CLKs 01 $8 \times$ ADC10CLKs 10 $16 \times$ ADC10CLKs 11 $64 \times$ ADC10CLKs
<b>ADC10SR</b>	Bit 10	ADC10 sampling rate. This bit selects the reference buffer drive capability for the maximum sampling rate. Setting ADC10SR reduces the current consumption of the reference buffer. 0 Reference buffer supports up to $\sim 200$ ksp/s 1 Reference buffer supports up to $\sim 50$ ksp/s
<b>REFOUT</b>	Bit 9	Reference output 0 Reference output off 1 Reference output on. Devices with $V_{eREF+} / V_{REF+}$ pin only.
<b>REFBURST</b>	Bit 8	Reference burst. 0 Reference buffer on continuously 1 Reference buffer on only during sample-and-conversion
<b>MSC</b>	Bit 7	Multiple sample and conversion. Valid only for sequence or repeated modes. 0 The sampling requires a rising edge of the SHI signal to trigger each sample-and-conversion. 1 The first rising edge of the SHI signal triggers the sampling timer, but further sample-and-conversions are performed automatically as soon as the prior conversion is completed
<b>REF2_5V</b>	Bit 6	Reference-generator voltage. REFON must also be set. 0 1.5 V 1 2.5 V
<b>REFON</b>	Bit 5	Reference generator on 0 Reference off 1 Reference on
<b>ADC10ON</b>	Bit 4	ADC10 on 0 ADC10 off 1 ADC10 on
<b>ADC10IE</b>	Bit 3	ADC10 interrupt enable 0 Interrupt disabled 1 Interrupt enabled
<b>ADC10IFG</b>	Bit 2	ADC10 interrupt flag. This bit is set if ADC10MEM is loaded with a conversion result. It is automatically reset when the interrupt request is accepted, or it may be reset by software. When using the DTC this flag is set when a block of transfers is completed. 0 No interrupt pending 1 Interrupt pending
<b>ENC</b>	Bit 1	Enable conversion 0 ADC10 disabled 1 ADC10 enabled
<b>ADC10SC</b>	Bit 0	Start conversion. Software-controlled sample-and-conversion start. ADC10SC and ENC may be set together with one instruction. ADC10SC is reset automatically. 0 No sample-and-conversion start 1 Start sample-and-conversion



### 22.3.2 ADC10CTL1, ADC10 Control Register 1

15	14	13	12	11	10	9	8
INCHx				SHSx		ADC10DF	ISSH
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
ADC10DIVx			ADC10SSELx		CONSEQx		ADC10BUSY
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	r-0

Can be modified only when ENC = 0

<b>INCHx</b>	Bits 15-12	Input channel select. These bits select the channel for a single-conversion or the highest channel for a sequence of conversions. Only available ADC channels should be selected. See device specific data sheet.
	0000	A0
	0001	A1
	0010	A2
	0011	A3
	0100	A4
	0101	A5
	0110	A6
	0111	A7
	1000	$V_{eREF+}$
	1001	$V_{REF-}/V_{eREF-}$
	1010	Temperature sensor
	1011	$(V_{CC} - V_{SS}) / 2$
	1100	$(V_{CC} - V_{SS}) / 2$ , A12 on MSP430F22xx devices
	1101	$(V_{CC} - V_{SS}) / 2$ , A13 on MSP430F22xx devices
	1110	$(V_{CC} - V_{SS}) / 2$ , A14 on MSP430F22xx devices
	1111	$(V_{CC} - V_{SS}) / 2$ , A15 on MSP430F22xx devices
<b>SHSx</b>	Bits 11-10	Sample-and-hold source select.
	00	ADC10SC bit
	01	Timer_A.OUT1 <sup>(1)</sup>
	10	Timer_A.OUT0 <sup>(1)</sup>
	11	Timer_A.OUT2 (Timer_A.OUT1 on MSP430F20x0, MSP430G2x31, and MSP430G2x30 devices) <sup>(1)</sup>
<b>ADC10DF</b>	Bit 9	ADC10 data format
	0	Straight binary
	1	2s complement
<b>ISSH</b>	Bit 8	Invert signal sample-and-hold
	0	The sample-input signal is not inverted.
	1	The sample-input signal is inverted.
<b>ADC10DIVx</b>	Bits 7-5	ADC10 clock divider
	000	/1
	001	/2
	010	/3
	011	/4
	100	/5
	101	/6
	110	/7
	111	/8
<b>ADC10SSELx</b>	Bits 4-3	ADC10 clock source select
	00	ADC10OSC
	01	ACLK
	10	MCLK
	11	SMCLK

<sup>(1)</sup> Timer triggers are from Timer0\_Ax if more than one timer module exists on the device.

### 22.3.3 ADC10AE0, Analog (Input) Enable Control Register 0

7	6	5	4	3	2	1	0
ADC10AE0x							
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

<b>ADC10AE0x</b>	Bits 7-0	ADC10 analog enable. These bits enable the corresponding pin for analog input. BIT0 corresponds to A0, BIT1 corresponds to A1, etc. The analog enable bit of not implemented channels should not be programmed to 1.
	0	Analog input disabled
	1	Analog input enabled